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Speaker's Name: Carlos Simpson

Talk Title: Infinity categories and why they are useful, I

Date: 2 / 1 / 19 Time: 3 : 30 am (pm) (circle one)

Please summarize the lecture in 5 or fewer sentences: _____

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INFINITY CATEGORIES AND WHY THEY ARE USEFUL, I

CARLOS SIMPSON

1. MOTIVATION

The basic motivation is that we start with a Grothendieck site X . We know it is useful to think about sheaves on X , i.e. a functor $X^{op} \rightarrow \text{Set}$ satisfying a descent property.

It turns out that it is also desirable to look at “sheaves of spaces”, i.e. functors $X^{op} \rightarrow \text{Spaces}$ that satisfy a descent property. The theory of such objects was constructed by Jardine, using ideas of Joyal. To manipulate these objects, we need some kind of theory of ∞ -categories.

Similar problems had arisen previously, for example people wanted to consider sheaves valued in the derived category. In such contexts much progress was made without ∞ -categories, although the apparatus of ∞ -categories is useful.

2. LOCALIZATION OF CATEGORIES

What’s the basic phenomenon? The slogan is: “localization (of categories) creates homotopies”.

Start with a category \mathcal{C} , and choose a subset of maps W in \mathcal{C} . One wants to make a category $W^{-1}\mathcal{C}$ by “adjoining inverses” to the maps in W .

Example 2.1. Consider a category with objects X, Y, Z and $u, v: X \rightarrow Y$ and $f: Y \rightarrow Z$ such that $fu = fv$. If we “invert” f , then we force $u = v$.

Suppose there’s another object W and $g: Y \rightarrow W$ such that $gu = gv$, then if we invert g this also forces $u = v$. But now we’ve asked $u = v$ in two different ways. This creates an “ S^1 in the space of maps”. This could arise in “real life” in the following way.

You might have a fibered category $\mathcal{F} \rightarrow \mathcal{C}$ such that $f^*: \mathcal{F}_Z \xrightarrow{\sim} \mathcal{F}_Y$ and $g^*: \mathcal{F}_W \xrightarrow{\sim} \mathcal{F}_Y$. This will induce 2 natural isomorphism between the functors

$$u^*: \mathcal{F}_Y \xrightarrow{\sim} \mathcal{F}_X$$

$$v^*: \mathcal{F}_Y \xrightarrow{\sim} \mathcal{F}_X$$

which we denote $\psi_f: u^* \xrightarrow{\sim} v^*$ and $\psi_g: u^* \xrightarrow{\sim} v^*$. Combining them gives an automorphism $\psi_g^{-1} \circ \psi_f: u^* \xrightarrow{\sim} u^*$. This is the “loop around the S^1 ”.

Then \mathcal{F} , viewed as a functor from \mathcal{C} , factors through the localization $W^{-1}\mathcal{C}$. The loop discussed earlier is a non-trivial 2-morphism in $W^{-1}\mathcal{C}$.

In the world of ∞ -categories, there is a localization operation $\mathcal{C}, W \mapsto W^{-1}\mathcal{C}$. Even if \mathcal{C} is an ordinary category, the localization $W^{-1}\mathcal{C}$ will be an ∞ -category with homotopy in arbitrary degrees.

How does this relate to the localization we might be familiar with (e.g. derived categories), in which we don't deal with this? There is a truncation from ∞ -categories to 1-categories. The usual localization is the composition of the ∞ -categorical localization with this truncation, so it discards the higher homotopical information.

Example 2.2. For 2-categories, this operation crushes the category of maps between objects to its set of isomorphism classes.

The localization $W^{-1}\mathcal{C}$ was constructed by Dwyer-Kan, in fact in two ways: a general way, and the “hammock way”.

3. SIMPLICIAL CATEGORIES

First of all, what is it? It's a *simplicial category*. One can think of simplicial categories as a model for ∞ -categories. This means that it has a “set” (or maybe “Grothendieck universe”) of objects, and for all objects x, y there is a simplicial set $A_*(x, y)$ of maps between x and y . (Morally we are imagining a space of maps, but it's technically better to use simplicial sets as a model for spaces.) Furthermore, there is a composition

$$A_*(x, y) \times A_*(y, z) \rightarrow A_*(x, z).$$

Recall that

$$|A_*(x, y)| \times |A_*(y, z)| = |A_*(x, y) \times A_*(y, z)|.$$

The point of the degeneracies is to make this true! Hence we get a map of spaces

$$|A_*(x, y) \times A_*(y, z)| \rightarrow |A_*(x, z)|.$$

Example 3.1. Let W be the weak equivalences in \mathbf{sSets} . Let $\mathcal{S} = W^{-1}\mathbf{sSets}$. Then $\mathcal{S}_*(X, Y)$ is a simplicial set representing maps from X to Y , i.e.

$$|\mathcal{S}_*(X, Y)| \sim \text{Map}(|X|, |Y|).$$