

# Generating Functions for Sets of Lattice Points

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## The Frobenius Problem

Let  $a_1, \dots, a_d$  be positive integers such that  $\gcd(a_1, \dots, a_d) = 1$ .

Let  $S = \{\lambda_1 a_1 + \dots + \lambda_d a_d \mid \lambda_i \in \mathbb{Z}_{\geq 0}\}$ , the semi-group generated by the  $a_i$ 's.

Example:  $a_1 = 3, a_2 = 7$ . Then

$$S = \{0, 3, 6, 7, 9, 10, 12, 13, 14, \dots\}.$$

All sufficiently large integers are in  $S$ .

Questions:

1. What is the largest integer not in  $S$ ?
2. How many positive integers are not in  $S$ ?

Algorithmic slant: can we answer these questions "quickly"?

(Question 1 previously solved by Kannan)

## Our Approach: Generating Functions

Define

$$f(S; x) := \sum_{a \in S} x^a.$$

In our example,  $f(S; x) = 1 + x^3 + x^6 + x^7 + \dots$ .  
Want to find (quickly) a simple formula for  $f(S; x)$ .

To answer question 2 (how many positive integers are not in  $S$ ), specialize

$$\frac{1}{1-x} - f(S; x)$$

at  $x = 1$ .

$x = 1$  is a pole of the fractions.

Idea: look at points near 1.

In our example, we could write

$$f(S; x) = x^3 + x^6 + x^7 + x^9 + x^{10} + \frac{x^{12}}{1-x},$$

but this is too long, in general.

When  $d = 2$ , can get

$$f(S; x) = \frac{1 - x^{a_1 a_2}}{(1 - x^{a_1})(1 - x^{a_2})}.$$

When  $d = 3$ , can get

$$f(S; x) = \frac{\pm 6 \text{ monomials}}{(1 - x^{a_1})(1 - x^{a_2})(1 - x^{a_3})}. \quad (\text{Denham})$$

When  $d = 4$ , could have

$$f(S; x) = \frac{\sqrt{t} \text{ monomials}}{(1 - x^{a_1})(1 - x^{a_2})(1 - x^{a_3})(1 - x^{a_4})},$$

where  $t = \min\{a_1, a_2, a_3, a_4\}$ . (Székely, Wormald).

$\sqrt{t}$  is too many. We want something like  $\log t$  or  $(\log t)^{10}$ .

## “Quick” Algorithms

We want an algorithm that inputs  $a_1, a_2, \dots, a_d$  and outputs  $f(S; x)$ .

The *input size* is the number of bits needed to encode the input for the algorithm.

Here, input size is approximately

$$\begin{aligned} & (1 + \log_2(a_1)) + \dots + (1 + \log_2(a_d)) \\ &= d + \sum_{i=1}^d \log_2(a_i). \end{aligned}$$

An algorithm is *polynomial time* if there is a polynomial  $p$  such that the algorithm runs in at most  $p(\text{input size})$  steps.

## General Problem

Fix  $d$ .

Let  $c_1, \dots, c_n \in \mathbb{Z}^d$  and  $b_1, \dots, b_n \in \mathbb{Z}$  be given. Define a rational polyhedron  $P$  by

$$P = \{x \in \mathbb{R}^d \mid \langle c_i, x \rangle \leq b_i, \forall i\}.$$

Input size of  $P$  is approximately

$$nd + \sum \log_2 |c_{ij}| + \sum \log_2 |b_i|.$$

Let  $T$  be a linear transformation  $\mathbb{R}^d \rightarrow \mathbb{R}^k$ , such that  $T(\mathbb{Z}^d) \subset \mathbb{Z}^k$ .

Input size of  $T = (t_{ij})$  is approximately

$$dk + \sum \log_2 |t_{ij}|.$$

For  $S \in \mathbb{Z}^d$  define

$$f(S; \mathbf{x}) = \sum_{s=(s_1, \dots, s_d) \in S} x_1^{s_1} x_2^{s_2} \cdots x_d^{s_d} = \sum_{s \in S} \mathbf{x}^s.$$

**Corollary 1** For fixed  $d$ , there is a constant  $s = s(d)$  and a polynomial time algorithm which, given  $a_1, \dots, a_d$ , writes  $f(S; x)$  in the form

$$f(S; x) = \sum_{i \in I} \alpha_i \frac{x^{p_i}}{(1 - x^{q_{i1}}) \cdots (1 - x^{q_{is}})},$$

where  $\alpha_i \in \mathbb{Q}$  and  $p_i, q_{ij} \in \mathbb{Z}$ .

In particular, the number of terms is bounded by a polynomial in the input size.

We have  $s \approx d^d$ .

**Theorem 1** (Barvinok) For fixed  $d$ , there exists a polynomial time algorithm which, given a rational polyhedron  $P$ , computes  $f(S; \mathbf{x})$ , where  $S = P \cap \mathbb{Z}^d$ , in the form

$$\sum_{i \in I} \pm \frac{\mathbf{x}^{p_i}}{(1 - \mathbf{x}^{q_{i1}}) \cdots (1 - \mathbf{x}^{q_{id}})},$$

where  $p_i, q_{ij} \in \mathbb{Z}^d$ .

Example:  $P = \{x \mid 0 \leq x \leq N\}$ . Then

$$f(S; x) = 1 + x + \cdots + x^N = \frac{1}{1-x} - \frac{x^{N+1}}{1-x}.$$



## Applying to Frobenius Problem

$$S = \{\lambda_1 a_1 + \cdots + \lambda_d a_d \mid \lambda_i \in \mathbb{Z}_{\geq 0}\}.$$

Let  $T : (\lambda_1, \dots, \lambda_d) \mapsto \lambda_1 a_1 + \cdots + \lambda_d a_d$ . Then  $T(\mathbb{R}_{\geq 0}^d \cap \mathbb{Z}^d) = S$ .

Can't technically apply theorem unless  $P$  is bounded. But we can fix this, because only a bounded piece of  $S$  is interesting.

Let  $N$  be bigger than largest integer not in  $S$  (e.g.  $N = a_1 a_2 \cdots a_d$ ). Let

$$P = \{(\lambda_1, \dots, \lambda_d) \mid \lambda_i \geq 0 \text{ and } \sum_{i=1}^d \lambda_i a_i \leq N - 1\}.$$

Then

$$S = T(P \cap \mathbb{Z}^d) \dot{\cup} \{N, N + 1, \dots\}.$$

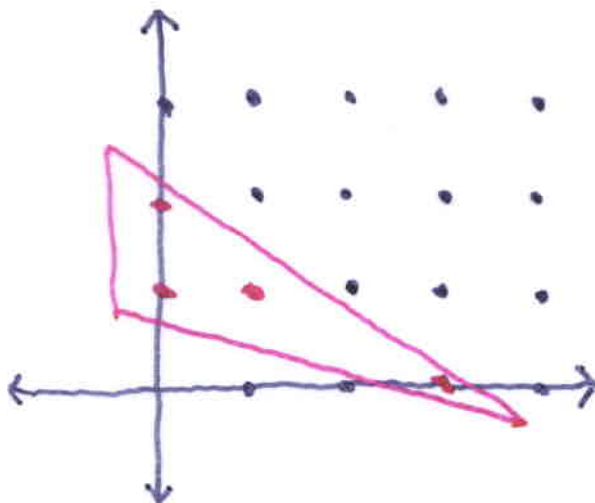
**Theorem 2 (-)** For fixed  $d$ , there exists a positive integer  $s = s(d)$  and a polynomial time algorithm which, given a rational polytope (i.e., bounded polyhedron)  $P$  and a linear transformation  $T : \mathbb{R}^d \rightarrow \mathbb{R}^k$  such that  $T(\mathbb{Z}^d) \subset \mathbb{Z}^k$ , computes  $f(S; \mathbf{x})$ , where  $S = T(P \cap \mathbb{Z}^d)$ , in the form

$$\sum_{i \in I} \alpha_i \frac{\mathbf{x}^{p_i}}{(1 - \mathbf{x}^{q_{i1}}) \cdots (1 - \mathbf{x}^{q_{is}})},$$

where  $\alpha_i \in \mathbb{Q}$  and  $p_i, q_{ij} \in \mathbb{Z}^d$ .

Usually,  $T$  is a projection of some sort.

Example:  $T(x, y) = x$ .



$$f(S, x) = 1 + x + x^3.$$

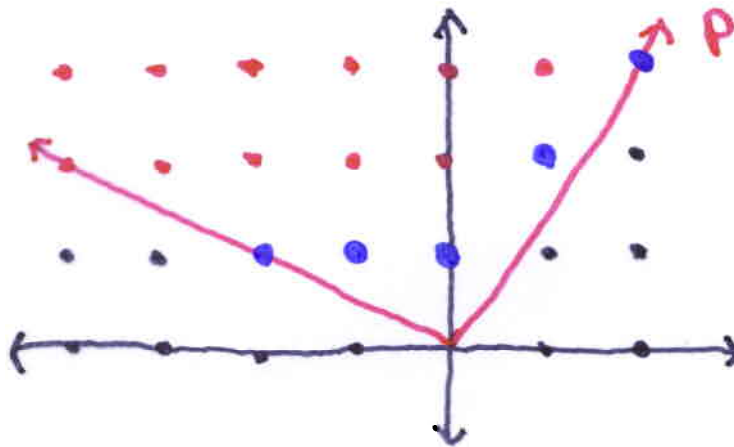
## Hilbert Bases

Let  $a_1, \dots, a_d \in \mathbb{Z}^d$  be linearly independent vectors.

Let  $K = \{\mu_1 a_1 + \dots + \mu_d a_d \mid \mu_i \in \mathbb{R}_{\geq 0}\}$ , the cone generated by  $a_1, \dots, a_d$ .

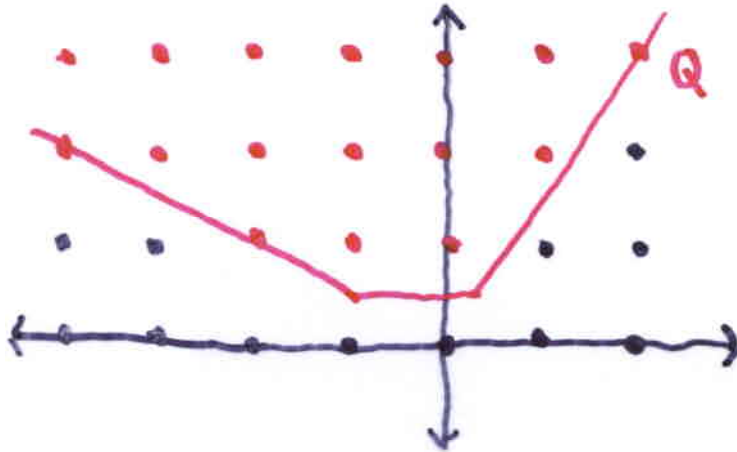
A *Hilbert Basis* is a set  $B \subset K \cap \mathbb{Z}^d$  such that every integer vector in  $K$  can be written as a nonnegative integer combination of the elements of  $B$ .

Example:  $d = 2, a_1 = (-2, 1), a_2 = (2, 3)$ .



In fact, this is the *Minimal Hilbert Basis* (the set of *indecomposable* integer vectors).

Let  $Q$  be a polyhedron such that  $Q \cap \mathbb{Z}^d = K \cap \mathbb{Z}^d \setminus 0$ .



Let  $P = Q \times Q$  and  $T : \mathbb{R}^{2d} \rightarrow \mathbb{R}^d$  be defined by  $T(x, y) = x + y$ .

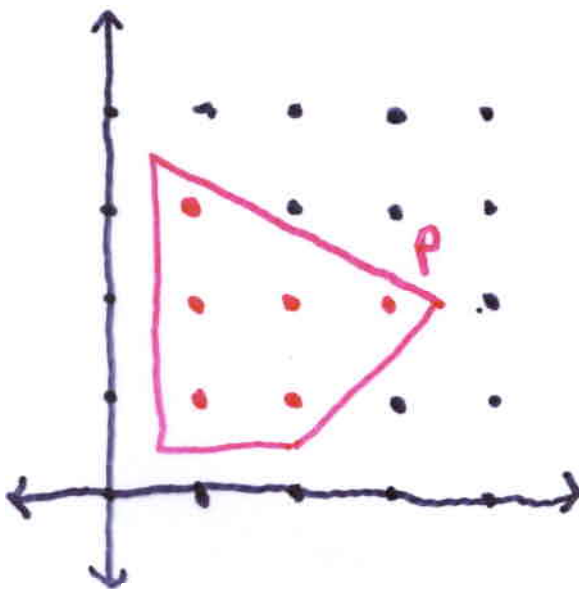
Let  $S_1 = T(P \cap \mathbb{Z}^{2d})$ , the set of *decomposable* integer vectors, and  $S_2 = Q \cap \mathbb{Z}^d$ .

Then  $MHB = S_2 \setminus S_1$  and

$$f(MHB; \mathbf{x}) = f(S_2; \mathbf{x}) - f(S_1; \mathbf{x}).$$

(Again, technically, we must deal with bounded sets.)

## Idea of Proof



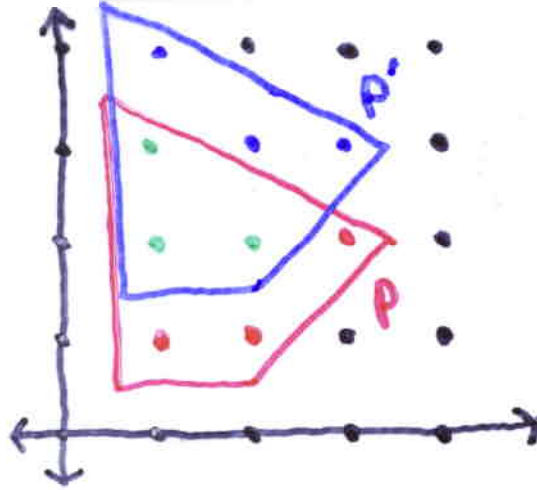
$T(x, y) = x$ . Let  $S = P \cap \mathbb{Z}^d$  and  $S' = T(S)$ .

$$f(S; x, y) = xy + xy^2 + xy^3 + x^2y + x^2y^2 + x^3y^2$$
$$f(S'; x) = x + x^2 + x^3.$$

$$f(S; x, 1) = 3x + 2x^2 + x^3.$$

This would work if the projection were 1-1.

“Play” with  $P$  so that the projection is 1-1.



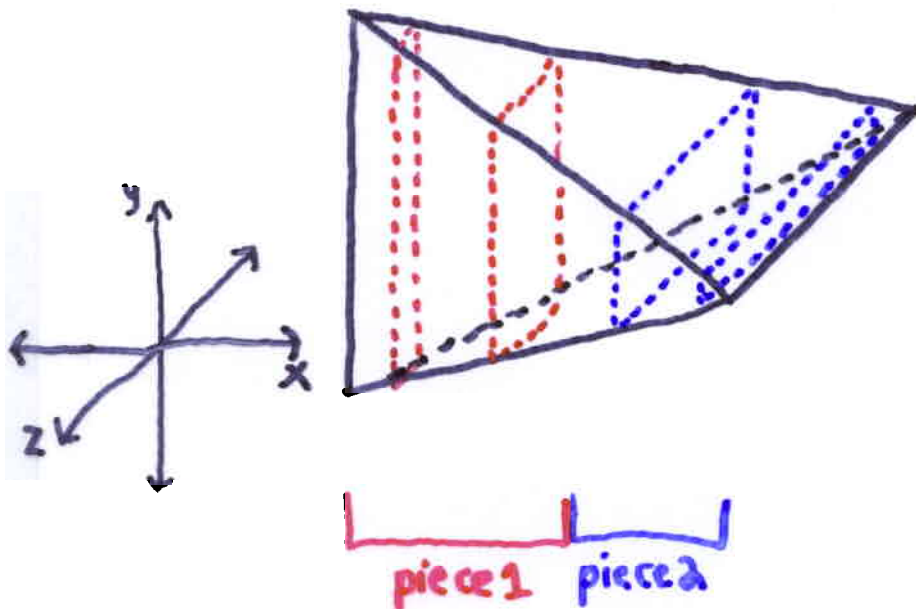
The projection of  $P \setminus P'$  is 1-1.

So  $f(S'; x) = f(P \setminus P'; x, 1)$ .

We can find  $f(P \setminus P'; x, y)$  using the following theorem:

**Theorem 3 (Barvinok)** For fixed  $d$ , if  $S_1$  and  $S_2$  are finite sets and we are given  $f(S_1; \mathbf{x})$  and  $f(S_2; \mathbf{x})$  in the usual form, we can compute  $f(S_1 \cap S_2; \mathbf{x})$ ,  $f(S_1 \cup S_2; \mathbf{x})$ , and  $f(S_1 \setminus S_2; \mathbf{x})$  in polynomial time.

For projections with kernel of  $\dim > 1$ , use following tool (Kannan; Kannan, Lovász, Scarf):



$$T(x, y, z) = x.$$

$$\text{width}(B, v) := \max_{x \in B} \langle v, x \rangle - \min_{x \in B} \langle v, x \rangle.$$

$$\text{width}(B) := \min_{v \in \mathbb{Z}^d} \text{width}(B, v).$$

Can divide image into pieces such that, in each piece, the fibers are almost the thinnest in a particular direction.

Find  $f(S \cap \text{Piece}_1; x)$  and  $f(S \cap \text{Piece}_2; x)$  separately.  
 $f(S; x)$  is the sum.